

## AMiRo-OS - Feature #585

### Investigate whether CAN can be an optional feature of AMiRo-OS

2019-02-25 16:50 - Thomas Schöpping

<b>Status:</b>	Resolved	<b>Start date:</b>	2019-02-25
<b>Priority:</b>	Low	<b>Due date:</b>	2019-05-01
<b>Assignee:</b>	Thomas Schöpping	<b>% Done:</b>	100%
<b>Category:</b>		<b>Estimated time:</b>	2.00 hours
<b>Target version:</b>			
<b>Description</b>			
So far, having a CAN bus enabled is mandatory for AMiRo-OS to work. The necessity for this should be investigated again and - if possible - this requirement should be removed.			

#### History

##### #1 - 2019-03-04 12:39 - Thomas Schöpping

- Status changed from New to Resolved

- % Done changed from 0 to 100

CAN is now optional.  
See commit:75c1f470 for details.